

# DeepONet: Learning nonlinear operators

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# From function to operator

- Function:  $\mathbb{R}^{d_1} \rightarrow \mathbb{R}^{d_2}$

e.g., image classification:



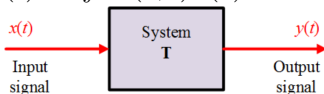
$\mapsto 5$

- Operator: function ( $\infty$ -dim)  $\mapsto$  function ( $\infty$ -dim)

e.g., derivative (local):  $x(t) \mapsto x'(t)$

e.g., integral (global):  $x(t) \mapsto \int K(s, t)x(s)ds$

e.g., dynamic system:



e.g., biological system

e.g., social system

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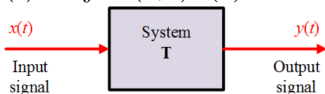
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$\Rightarrow$  Can we learn operators via neural networks?

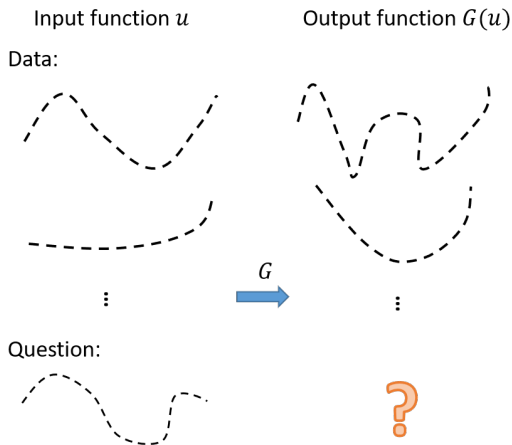
$\Rightarrow$  How?



# Problem setup

$$G : u \in V \subset C(K_1) \mapsto G(u) \in C(K_2)$$

$$G(u) : y \in \mathbb{R}^d \mapsto G(u)(y) \in \mathbb{R}$$



# Universal Approximation Theorem for Operator

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## Theorem (Chen & Chen, 1995)

Suppose that  $\sigma$  is a continuous non-polynomial function,  $X$  is a Banach Space,  $K_1 \subset X$ ,  $K_2 \subset \mathbb{R}^d$  are two compact sets in  $X$  and  $\mathbb{R}^d$ , respectively,  $V$  is a compact set in  $C(K_1)$ ,  $G$  is a continuous operator, which maps  $V$  into  $C(K_2)$ .

Then for any  $\epsilon > 0$ , there are positive integers  $n, p, m$ , constants  $c_i^k, \xi_{ij}^k, \theta_i^k, \zeta_k \in \mathbb{R}$ ,  $w_k \in \mathbb{R}^d$ ,  $x_j \in K_1$ ,  $i = 1, \dots, n$ ,  $k = 1, \dots, p$ ,  $j = 1, \dots, m$ , such that

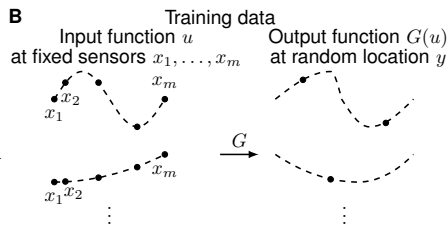
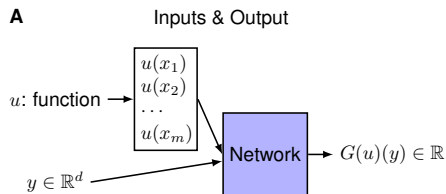
$$\left| G(u)(y) - \sum_{k=1}^p \sum_{i=1}^n c_i^k \sigma \left( \sum_{j=1}^m \xi_{ij}^k u(x_j) + \theta_i^k \right) \sigma(w_k \cdot y + \zeta_k) \right| < \epsilon$$

holds for all  $u \in V$  and  $y \in K_2$ .

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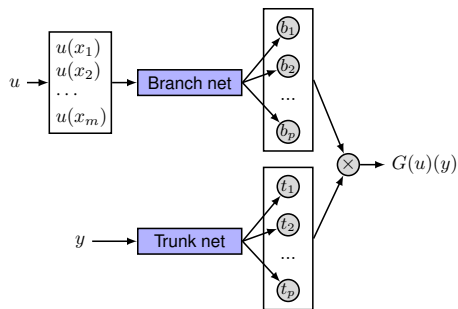


- Inputs:  $u$  at sensors  $\{x_1, x_2, \dots, x_m\} \in \mathbb{R}^m$ ,  $y \in \mathbb{R}^d$
- Output:  $G(u)(y) \in \mathbb{R}$

# Deep operator network (DeepONet)

$$G(u)(y) \approx \sum_{k=1}^p \underbrace{b_k(u)}_{\text{branch}} \underbrace{t_k(y)}_{\text{trunk}}$$

D Unstacked DeepONet



**Idea:**  $G(u)(y)$ : a function of  $y$  conditioning on  $u$

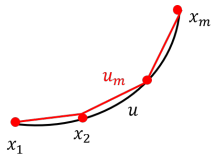
- $t_k(y)$ : basis function of  $y$
- $b_k(u)$ :  $u$ -dependent coefficient, i.e., functional of  $u$

## Error analysis: the number of sensors

Consider  $G : u(x) \mapsto \mathbf{s}(x)$  ( $x \in [0, 1]$ ) by ODE system

$$\frac{d}{dx} \mathbf{s}(x) = \mathbf{g}(\mathbf{s}(x), u(x), x), \quad \mathbf{s}(0) = \mathbf{s}_0$$

$$\forall u \in V \Rightarrow u_m \in V_m$$



Let  $\kappa(m, V) := \sup_{u \in V} \max_{x \in [0, 1]} |u(x) - u_m(x)|$

e.g., Gaussian process with kernel  $e^{-\frac{\|x_1 - x_2\|^2}{2l^2}}$ :  $\kappa(m, V) \sim \frac{1}{m^2 l^2}$

**Theorem (Lu et al., *Nature Mach Intell*, 2021)**

*Assume  $\mathbf{g}$  is Lipschitz continuous ( $c$ ).*

*Then there exists a DeepONet  $\mathcal{N}$ , such that*

$$\sup_{u \in V} \max_{x \in [0, 1]} \|G(u)(x) - \mathcal{N}([u(x_1), \dots, u(x_m)], x)\|_2 < ce^c \kappa(m, V).$$

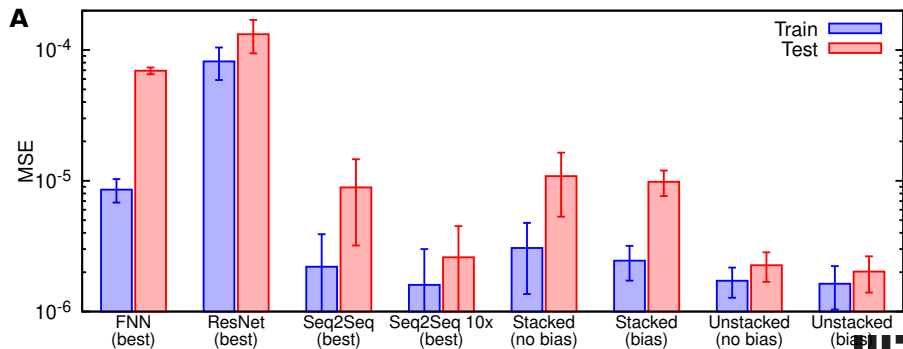


# Explicit operator: A simple ODE case

$$\frac{ds(x)}{dx} = u(x), \quad x \in [0, 1], \quad s(0) = 0$$

$$G : u(x) \mapsto s(y) = s(0) + \int_0^y u(\tau) d\tau$$

Very small generalization error!

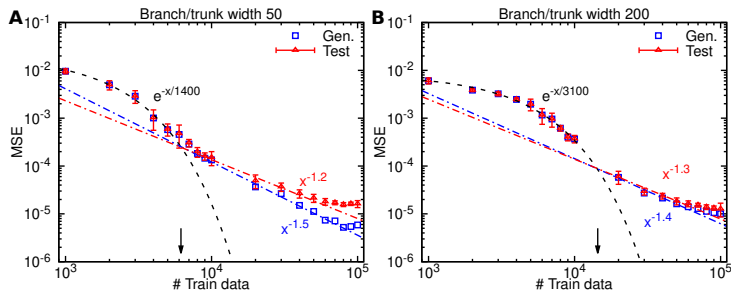


Lu et al., *Nature Mach Intell*, 2021

# Implicit operator: Gravity pendulum with an external force

$$\frac{ds_1}{dt} = s_2, \quad \frac{ds_2}{dt} = -k \sin s_1 + u(t)$$

$$G : u(t) \mapsto \mathbf{s}(t)$$



Test/generalization error:

- small dataset: exponential convergence
- large dataset: polynomial rates
- larger network has later transition point

Lu et al., *Nature Mach Intell*, 2021

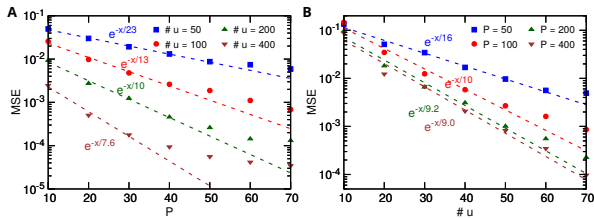


# Implicit operator: Diffusion-reaction system

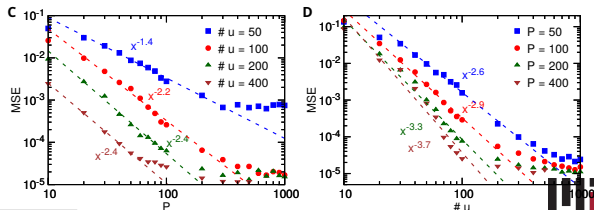
$$\frac{\partial s}{\partial t} = D \frac{\partial^2 s}{\partial x^2} + ks^2 + u(x), \quad x \in [0, 1], t \in [0, 1]$$

# Training points = # $u \times P$

Small dataset:  
Exponential convergence



Large dataset:  
Polynomial convergence



Lu et al., *Nature Mach Intell*, 2021

# Stochastic PDE

Consider the elliptic problem with multiplicative noise

$$-\operatorname{div}(e^{b(x;\omega)} \nabla u(x;\omega)) = f(x), \quad x \in (0, 1)$$

with zero boundary conditions,  $f(x) = 10$ .

Stochastic process  $b(x;\omega) \sim \mathcal{GP}(0, \sigma^2 \exp(-\|x_1 - x_2\|^2 / 2l^2))$

$$G : b(x;\omega) \mapsto u(x;\omega)$$

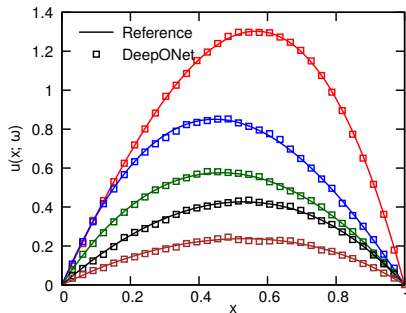
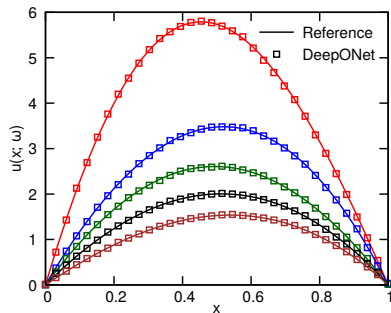
## Ideas:

- Karhunen-Loève (KL) expansion:  $b(x;\omega) \approx \sum_{i=1}^N \sqrt{\lambda_i} e_i(x) \xi_i(\omega)$
- branch net inputs:  $[\sqrt{\lambda_1} e_1(x), \sqrt{\lambda_2} e_2(x), \dots, \sqrt{\lambda_N} e_N(x)] \in \mathbb{R}^{N \times m}$ ,  
where  $\sqrt{\lambda_i} e_i(x) = \sqrt{\lambda_i} [e_i(x_1), e_i(x_2), \dots, e_i(x_m)] \in \mathbb{R}^m$
- trunk net inputs:  $[x, \xi_1, \xi_2, \dots, \xi_N] \in \mathbb{R}^{N+1}$



# Stochastic PDE

Example: 10 different random samples of  $u(x; \omega)$  for  $b(x; \omega)$  with  $l = 1.5$



# DeepONet for learning operators

DeepONet (Lu et al., *Nature Mach Intell*, 2021)

## • Algorithms & Applications

- ▶ 16 ODEs/PDEs (nonlinear, fractional & stochastic)
- ▶ Multiphysics & Multiscale problems
  - ★ Bubble growth dynamics from nm to mm (*J Chem Phys*, 2021)
  - ★ Hypersonics (arXiv:2011.03349)
  - ★ Electroconvection (arXiv:2009.12935)

## • Observation: Good performance

- ▶ Small generalization error
- ▶ Exponential/polynomial error convergence

## • Theory

- ▶ Convergence rate for advection-diffusion equations (arXiv:2102.10621)



# DeepM&Mnet: Multiphysics & Multiscale problems

Hypersonics: Coupled flow and finite-rate chemistry behind a normal shock  
(arXiv:2011.03349)

